PS 2010: 12. Matrix Algebra 1

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• Homework 6 due next week

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Agenda

- Matrix
- OLS estimator in matrix form

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Definition: A rectangular array of numbers is called a matrix

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Matrix

$$
A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}
$$

- The horizontal arrays of a matrix are called its rows and the vertical arrays are called its columns.
- A matrix having m rows and n columns is said to have the order $m \times n$
- A matrix having only one column is called a column vector; and a matrix with only one row is called a row vector.

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• Matrix can also be represented as $[a_{ij}]$

Special Matrices

• Zero-matrix: a matrix in which each entry is zero

$$
\bm{0}_{2\times 2} = \left[\begin{array}{cc} 0 & 0 \\ 0 & 0 \end{array}\right]
$$

- Square matrix: a matrix having the number of rows equal to the number of columns
- Symmetric matrix: one in which $a_{ij} = a_{ji}$ for all i and j

$$
\mathbf{A} = \left[\begin{array}{ccc} 1 & .5 & 2 \\ .5 & 1 & .75 \\ 2 & .75 & 1 \end{array} \right]
$$

• A diagonal matrix is one in which the only non-zero entries appear along the main diagonal from upper-left to lower-right

$$
\Omega = \left[\begin{array}{cccc} 6.8 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2.5 \end{array} \right]
$$

Special Matrices

• A scalar matrix is one in which the same non-zero element appears along the main diagonal.

$$
\Sigma = \left[\begin{array}{ccc} .47 & 0 & 0 \\ 0 & .47 & 0 \\ 0 & .0 & .47 \end{array} \right]
$$

• The identity matrix I_n matrix is an $n \times n$ with 1' s along the main diagonal and 0's off the diagonal:

$$
I_3 = \left[\begin{array}{rrr} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right]
$$

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• A triangular matrix is one that has only zeros above or below the main diagonal. If the zeros are below, the matrix is upper triangular.

$$
\Psi = \left[\begin{array}{ccc} .97 & .75 & .69 \\ 0 & .82 & .52 \\ 0 & 0 & .32 \end{array} \right]
$$

• A partitioned matrix is one that is divided into submatrices

$$
\mathbf{Z} = \begin{bmatrix} 1.5 & .5 & 0 & 0 \\ .5 & 1.5 & 0 & 0 \\ \hline 0 & 0 & .5 & .75 \\ 0 & 0 & .75 & .5 \end{bmatrix} = \begin{bmatrix} \mathbf{Z}_{11} & \mathbf{Z}_{12} \\ \hline \mathbf{Z}_{21} & \mathbf{Z}_{22} \end{bmatrix}
$$

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Transpose of a Matrix

The transpose of an $m \times n$ (m by n) matrix is an $n \times m$ matrix whose (i, j) entry is the original matrix's (j, i) entry:

$$
\mathbf{X} = \left[\begin{array}{ccc} 0 & 1 & 0 \\ .5 & 0 & .5 \\ 0 & 1 & 0 \end{array} \right], \mathbf{X}' = \left[\begin{array}{ccc} 0 & .5 & 0 \\ 1 & 0 & 1 \\ 0 & .5 & 0 \end{array} \right]
$$

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Properties of Matrix Transposition

• Invertibility Property

$$
\left(\textbf{X}'\right)'=\textbf{X}
$$

• Additive Property

$$
(\textbf{X}+\textbf{Y})'=\textbf{X}'+\textbf{Y}'
$$

• Multiplicative Property

$$
(\bm{X}\bm{Y})'=\bm{Y}'\bm{X}'
$$

• Scalar Multiplication Property

$$
(c\mathbf{X})'=c\mathbf{X}'
$$

• Inverse Transpose Property

$$
\left(\textbf{X}^{-1}\right)'=\left(\textbf{X}'\right)^{-1}
$$

• Symmetric Matrix Property

$$
\mathbf{X}' = \mathbf{X}
$$

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Matrix Addition and Subtraction

- We define matrix addition and subtraction by the addition and subtraction of the corresponding elements of the matrices.
- Thus, we can only add and subtract matrices with the same dimensions.
- The addition (subtraction) of one $m \times n$ matrix by another $m \times n$ matrix produces an $m \times n$ matrix whose elements are the sums (differences) of the corresponding elements from the original matrices.

$$
Y+X=\begin{bmatrix} y_{11} & y_{12} & y_{13} \ y_{21} & y_{22} & y_{23} \ y_{31} & y_{32} & y_{33} \end{bmatrix} + \begin{bmatrix} x_{11} & x_{12} & x_{13} \ x_{21} & x_{22} & x_{23} \ x_{31} & x_{32} & x_{33} \end{bmatrix} = \begin{bmatrix} y_{11} + x_{11} & y_{12} + x_{12} & y_{13} + x_{13} \ y_{21} + x_{21} & y_{22} + x_{22} & y_{23} + x_{23} \ y_{31} + x_{31} & y_{32} + x_{32} & y_{33} + x_{33} \end{bmatrix}
$$

$$
Y-X=\begin{bmatrix} y_{11} & y_{12} & y_{13} \ y_{21} & y_{22} & y_{23} \ y_{31} & y_{32} & y_{33} \end{bmatrix} - \begin{bmatrix} x_{11} & x_{12} & x_{13} \ x_{21} & x_{22} & x_{23} \ x_{31} & x_{32} & x_{33} \end{bmatrix} = \begin{bmatrix} y_{11} - x_{11} & y_{12} - x_{12} & y_{13} - x_{13} \ y_{21} - x_{21} & y_{22} - x_{22} & y_{23} - x_{23} \ y_{31} - x_{31} & y_{32} - x_{32} & y_{33} - x_{33} \end{bmatrix}
$$

Multiplying an $m \times n$ matrix by a scalar produces an $m \times n$ matrix whose elements are the products of the scalar and each element of the matrix.

$$
\beta \times \mathbf{X} = \beta \times \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix} = \begin{bmatrix} \beta x_{11} & \beta x_{12} & \beta x_{13} \\ \beta x_{21} & \beta x_{22} & \beta x_{23} \\ \beta x_{31} & \beta x_{32} & \beta x_{33} \end{bmatrix}
$$

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Matrix Multiplication

- Let **A** be an $m \times n$ matrix and **B** be an $n \times p$ matrix. The matrix product $\mathbf{A}\mathbf{B}$ is an $m \times p$ matrix whose j^th column is Ab^j .
- Note that the inner dimensions of the two matrices must be equal (product conformable), and the outer dimensions determine the dimensions of the product.

$$
\mathbf{Wy} = \begin{bmatrix} 0 & 1 & 0 \\ .5 & 0 & .5 \\ 0 & 1 & 0 \end{bmatrix} \times \begin{bmatrix} 4 \\ 2 \\ 9 \end{bmatrix} = \begin{bmatrix} 0 \times 4 + 1 \times 2 + 0 \times 9 \\ .5 \times 4 + 0 \times 2 + .5 \times 9 \\ 0 \times 4 + 1 \times 2 + 0 \times 9 \end{bmatrix} = \begin{bmatrix} 2 \\ 6.5 \\ 2 \end{bmatrix}
$$

Matrix Multiplication Properties

If the matrices A, B, C are conformable for multiplication, then

• Associative Property

$$
(\text{AB})\text{C}=\text{A}(\mathrm{BC})
$$

• Distributive Property

$$
A(B+C)=AB+AC
$$

• Transpose of a Product

$$
(\mathbf{A}\mathbf{B})'=\mathbf{B}'\mathbf{A}'
$$

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Linear System

Definition: A linear system of m equations in n unknowns $x_1, x_2, ..., x_n$ is a set of equations of the form

$$
a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1
$$

\n
$$
a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2
$$

\n
$$
\vdots
$$

\n
$$
a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m
$$

\nwhere for $1 \le i \le n$, and $1 \le j \le m$; a_{ij} , $b_i \in R$

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Linear System

We rewrite the above equations in the form $Ax = b$, where

 $A =$ $\sqrt{ }$ $\begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \\ \begin{array}{c} \end{array} \end{array} \end{array}$ a_{11} a_{12} \cdots a_{1n} a_{21} a_{22} \cdots a_{2n} a_{m1} a_{m2} \cdots a_{mn} 1 $\begin{array}{c} \n\end{array}$ $, x =$ $\sqrt{ }$ $\begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \\ \begin{array}{c} \end{array} \end{array} \end{array}$ x_1 x_2 . . . xn 1 , and $\mathbf{b} =$ $\sqrt{ }$ $\begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \\ \begin{array}{c} \end{array} \end{array} \end{array}$ b_1 $b₂$. . . b_m 1 $\begin{array}{c} \n\downarrow \\
\downarrow \\
\downarrow\n\end{array}$

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Rank of Matrix

Definition: The number of non-zero rows in the row reduced form of a matrix A is called the rank of A, denoted $rank(A)$.

$$
\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
$$

$$
\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}
$$

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Inverse of a Matrix

• An $n \times n$ matrix **A** is invertible if there is an $n \times n$ matrix **B** such that $AB = BA = I_n$. B is the inverse of A, and, typically, we write $\, {\bf B} \,$ as $\, {\bf A}^{-1}. \,$

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- $(A^{-1})^{-1} = A$.
- $(AB)^{-1} = B^{-1}A^{-1}.$
- $(A')^{-1} = (A^{-1})'$
- See R example

Equivalent conditions for Invertibility

For a $n \times n$ square matrix A, the following statements are equivalent:

- A is full rank means rank $(A) = n$.
- A is invertiable means A is full rank

Ordinary Least Squares (OLS)

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Suppose we have data on education level and income and want to know their relationship.

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The goal is to find a line that best describe the linear relationship

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We minimize the distance between line and data points

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Let's formalize our idea a little bit

$$
\begin{bmatrix}\nY_1 \\
Y_2 \\
\vdots \\
Y_n\n\end{bmatrix}_{n\times 1} = \begin{bmatrix}\n1 & X_{11} & X_{12} & \dots & X_{1k} \\
1 & X_{21} & X_{22} & \dots & X_{2k} \\
\vdots & \vdots & \vdots & \dots & \vdots \\
1 & X_{n1} & X_{n2} & \dots & X_{nk}\n\end{bmatrix}_{n\times k} \begin{bmatrix}\n\beta_1 \\
\beta_2 \\
\vdots \\
\beta_k\n\end{bmatrix}_{k\times 1} + \begin{bmatrix}\ne_1 \\
e_2 \\
\vdots \\
e_n\n\end{bmatrix}_{n\times 1}
$$

Which can be simplified as

$$
y = X\beta + e
$$

Our job is to find $\hat{\beta}$

$$
y = X\hat{\beta} + \epsilon
$$

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- Our goal is to minimize the sum of distance
- One way is to minimize the sum of the squared distance
- That is $\epsilon' \epsilon$
- We have $\epsilon = v X\hat{\beta}$

$$
\begin{bmatrix} \epsilon_1 & \epsilon_2 & \dots & \epsilon_n \end{bmatrix}_{1 \times n} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{bmatrix}_{n \times 1} = [\epsilon_1 \times \epsilon_1 + \epsilon_2 \times \epsilon_2 + \dots + \epsilon_n \times \epsilon_n]_{1 \times 1}
$$

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$$
\epsilon'\epsilon = (y - X\hat{\beta})'(y - X\hat{\beta})
$$

= $y'y - \hat{\beta}'X'y - y'X\hat{\beta} + \hat{\beta}'X'X\hat{\beta}$
= $y'y - 2\hat{\beta}'X'y + \hat{\beta}'X'X\hat{\beta}$

Where $\hat{\beta}^{\prime}X^{\prime}y$ and $y^{\prime}X\hat{\beta}$ are scalars. Therefore, an inverse of a scalar is itself.

So, the goal is to find $\hat{\beta}$ that minimize the above equation

$$
\epsilon'\epsilon = y'y - 2\hat{\beta}'X'y + \hat{\beta}'X'X\hat{\beta}
$$

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If a and b are $K \times 1$ vectors.

$$
\frac{\partial a'b}{\partial b} = \frac{\partial b'a}{\partial b} = a
$$

$$
\frac{\partial b'Ab}{\partial b} = 2Ab = 2b'A
$$

$$
\frac{\partial 2\beta' X'y}{\partial b} = \frac{\partial 2\beta'(X'y)}{\partial b} = 2X
$$

Therefore,

$$
\frac{\partial \beta' X' X \beta}{\partial b} = \frac{\partial \beta' A \beta}{\partial b} = 2A\beta = 2X'X\beta
$$

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OLS Estimator

$$
\frac{\partial \epsilon' \epsilon}{\partial \hat{\beta}} = -2X'y + 2X'X\hat{\beta} = 0
$$

Then

$$
X'X\hat{\beta}=X'y
$$

Finally

$$
\hat{\beta}=(X'X)^{-1}X'y
$$

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Assumptions

- We make no assumptions to derive OLS estimator
- However, we need make some assumptions to guarantee OLS is BLUE

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• And allow us to do inference

Gauss-Markov Assumptions

• Assumption 1: Linear relationship between dependent and independent variables

$$
y = X\beta + e
$$

• **Assumption 2:** No perfect multicollinearity in independent variables

$$
rank(X)=k
$$

• **Assumption 3:** Strict exogeneity or zero conditional mean assumption

$$
E(e \mid X) = 0
$$

- **Assumption 4:** Spherical error variance
	- Homoskedasticity: $E(e'e | X) = \sigma^2$
	- No autocorrelation: $E(e_i e_j | X) = 0$ for i, $j = 1, 2, 3, ...; i \neq j$

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Unbiaseness

- The Gauss-Markov Assumptions guarantee OLS estimator is BLUE
- Unbiasedness:

$$
\hat{\beta} = (X'X)^{-1}X'y
$$

\n
$$
\hat{\beta} = (X'X)^{-1}X'(X\beta + e)
$$

\n
$$
\hat{\beta} = (X'X)^{-1}X'X\beta + (X'X)^{-1}X'e
$$

\n
$$
\hat{\beta} = \beta + (X'X)^{-1}X'e
$$

\n
$$
E[\hat{\beta}] = E[\beta + (X'X)^{-1}X'e]
$$

\n
$$
= \beta + (X'X)^{-1}X'E[e]
$$

- $E[e] = 0$ by assumption
- Therefore, we have $E[\hat{\beta}] = \beta$